

IMPROVED PATTERN GENERATOR

Field of the invention

The present invention relates to printing of patterns with extremely high precision on photosensitive surfaces, such as photomasks for semiconductor devices and displays. It also relates to direct writing of semiconductor device patterns, display panels, integrated optical devices and electronic interconnect structures. Furthermore, it can have applications to other types of precision printing such as security printing. The term printing should be understood in a broad sense, meaning exposure of photoresist and photographic emulsion, but also the action of light on other light sensitive media such as dry-process paper, by ablation or chemical processes activated by light or heat. Light is not limited to mean visible light, but a wide range of wavelengths from infrared (IR) to extreme UV. Of special importance is the ultraviolet range from 370 nm (UV) through deep ultraviolet (DUV), vacuum ultraviolet (VUV) and extreme ultraviolet (EUV) down to a few nanometers wavelength. EUV is in this application defined as the range from 100 nm and down as far as the radiation is possible to treat as light. A typical wavelength for EUV is 13 nm. IR is defined as 780 nm up to about 20 μ m.

In a different sense the invention relates to the art and science of spatial light modulators and projection displays and printers using such modulators. In particular it improves the grey-scale properties, the image stability through focus and image uniformity and the data processing for such modulators by application of analog modulation technique. The most important use of the analog modulation is to generate an image in a high-contrast material such as photoresist with an address

grid, i.e. the increment by which the position of an edge in the pattern is specified, that is much finer than the grid created by the pixels of the spatial light modulator.

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Background of the invention

It is known in the current art to build precision pattern generators using projection of micromirror spatial light modulators (SLMs) of the micromirror type 10 (Nelson 1988, Kück 1990). To use an SLM in a pattern generator has a number of advantages compared to the more wide-spread method of using scanning laser spots: the SLM is a massively parallel device and the number of pixels that can be written per second is extremely high. The 15 optical system is also simpler in the sense that the illumination of the SLM is non-critical, while in a laser scanner the entire beam path has to be built with high precision. Compared to some types of scanners, in particular electrooptic and acoustooptic ones, the 20 micromirror SLM can be used at shorter wavelengths since it is a purely reflective device.

In both references cited above the spatial modulator uses only on-off modulation at each pixel. The input data is converted to a pixel map with one bit depth, i.e. with 25 the values 0 and 1 in each pixel. The conversion can be done effectively using graphic processors or custom logic with area fill instructions.

In a previous application by the same inventor Sandström (Sandström et. al. 1990), the ability to use an 30 intermediate exposure value at the boundary of a pattern element to fine-adjust the position of the element's edge in the image created by a laser scanner was described.

It is also known in the art to create a grey-scale image, preferably for projection display of video images 35 and for printing, with an SLM by variation of the time a pixel is turned on or by printing the same pixel several times with the pixel turned on a varying number of times.

The present invention devices a system for direct grey-scale generation with a spatial light modulator, with a special view to the generation of ultra-precision patterns. Important aspects in the preferred embodiments, 5 are uniformity of the image from pixel to pixel and independence of exact placement of a feature relative to the pixels of the SLM and stability when focus is changed, either with intention or inadvertently.

10 Summary of the invention

It is therefore an object of the present invention to provide an improved pattern generator for printing of precision patterns.

15 This object is achieved with an apparatus according to the appended claims, providing an analog modulation of the pixels in the SLM.

Brief description of the drawings

20 Figure 1 shows a printer in prior art. The SLM consists of micromirrors that deflect the light from the lens pupil.

Figure 2 shows a number of pixel designs with the upper four pixels in an off state and the remaining five pixels turned on.

25 Figure 3 shows an array of pixels moving up and down like pistons, thereby creating a phase difference. This is how an edge can be fine-positioned with a phase-type SLM.

Figure 4 shows a schematic comparison between an SLM 30 with deflecting mirrors and an SLM with deforming mirrors.

Figure 5 shows a flow diagram of a method for translating and feeding data to the SLM.

35 Figure 6 shows a preferred embodiment of a pattern generator according to the invention.

Figure 7 shows schematically possible complex amplitudes for different types of SLM.

Figure 8 shows schematically different types of controlling of the SLM mirrors.

Figure 9 shows an example of an alignment mark to be used in the invention.

5 Figure 10 shows schematically an example of an detection and alignment system according to an embodiment of the invention.

Figure 11 shows schematically an example of an alignment method according to the invention.

10 Figure 12 shows schematically an example of a beam measuring mark to be used in the invention.

Figure 13 shows schematically a first example of an embodiment of the detection and alignment system according to the invention comprising field reduction 15 means.

Figure 14 shows schematically a second example of an embodiment of the detection and alignment system according to the invention comprising field reduction means.

20 Figure 15 shows schematically an analog arrangement of reflecting surfaces to be used in an embodiment of the invention.

Description of the invention

25 The basis for understanding the invention is the generic arrangement in Figure 1 which shows a generic projection printer with an SLM. Spatial light modulators based on reflection come in two varieties, the deflection type (Nelson) and the phase type (Kück). The difference 30 between them may in a particular case with micromirrors seem small, but the phase SLM extinguishes the beam in the specular direction by destructive interference, while a pixel in a deflection SLM deflects the specular beam geometrically to one side so that it misses the aperture 35 of the imaging lens as shown in figure 1. For ultra-precise printing as performed in the current invention the phase-modulating system as described by Kück 1990 is

superior to the deflecting type. First, it has better contrast since all parts of the surface, also hinges and support posts, take part in the destructive interference and total extinction can be achieved. Second, a system that works by deflecting the light to the side is difficult to make symmetrical around the optical axis at intermediate deflection angles, creating a risk of feature instability when focus is changed. In the preferred embodiments the phase type is used, but if one accepts or designs around the asymmetry of the deflection type it could also be used. This is illustrated schematically in fig 4. In the first figure, 4a, a non-deflected micromirror 401 is illuminated, and the reflected light is not directed towards the aperture 402, and, hence, the light does not reach the substrate 403. In fig 4b, on the other hand, the mirror is fully deflected, and all the reflected light are directed towards the aperture. In an intermediate position only part of the reflected light will reach the substrate, which is shown in fig 4c. However, in this case the light is not symmetrical around the optical axis for the lens 404, and there is an oblique incidence on the substrate. Hereby the distance between the lens and the substrate area becomes very critical, and small changes, such as the one being indicated by the dashed position for area, causes significant displacements of the features on the substrate. A way to solve this problem is indicated by the fig 4d-f. Here, a first exposure is made with a first deflection angle for the micromirror, and thereafter a second exposure, preferably with the same light dose, is made for a second deflection angle, being complementary to the first angle. Hereby, the combination of the first and second exposure is symmetrical around the optical axis for the lens. Another way to solve the problem is to use deforming mirror 401', such as is shown in fig 4g, whereby the reflected light is evenly distributed over aperture. This last figure could schematically represent

two cases, a phase type SLM (described below) or a deflection SLM, where light is reflected from different parts of the mirror.

The phase SLM can be built either with micromachined mirrors, so called micromirrors, or with a continuous mirror surface on a supporting substrate that is possible to deform using an electronic signal. In Kück 1990 a viscoelastic layer controlled by an electrostatic field is used, but it is equally possible, especially for very short wavelengths where deformations of the order of a few nanometer are sufficient, to use a piezoelectric solid disk that is deformed by electric field or another electrically, magnetically or thermally controlled reflecting surface. For the remainder of this application an electrostatically controlled micromirror matrix (one- or two-dimensional) is assumed, although other arrangements as described above are possible, such as transmissive or reflecting SLMs relying on LCD crystals or electrooptical materials as their modulation mechanism, or micromechanical SLMs using piezoelectric or electrostrictive actuation.

The invention preferably uses a micromirror where the phase modulation is variable to obtain a variable amount of light reaching the pupil of the projection lens. Figure 2 shows some multi-element mirrors. The tilts of the various parts of the mirrors are unimportant. In fact one element by itself would direct the light toward the lens while another would direct it outside of the pupil. The correct way to understand the function is to look at the complex amplitude reaching the center of the pupil from each infinitesimal area element of the mirror and integrate the amplitude over the mirror. With a suitable shape of the mirror it is possible to find a deformation where the complex amplitudes add up to almost zero, corresponding to no light reaching the pupil. This is the off-state of the micromirror, while a relaxed state where the mirror

surface is flat and the complex amplitudes add in phase is the on-state. Between the on and off-states the amount of light in the specular direction is a continuous but non-linear function of the deformation.

5 The pattern to be written is normally a binary pattern, such as a photomask pattern in chrome on a glass substrate. In this context binary means that there are no intermediate areas: a certain point on the photomask surface is either dark (covered with chrome) or clear (no chrome). The pattern is exposed in photoresist by the projected image from the SLM and the photoresist is developed. Modern resists have high contrast, meaning that a small percentage change in exposure makes the difference between full removal of the resist in the 10 developer and hardly any removal at all. Therefore the photoresist has an edge that is normally almost perpendicular to the substrate surface, even though the aerial image has a gradual transition between light and dark. The chrome etching does further increase the 15 contrast, so that the resulting image is perfectly binary: either opaque or clear with no intermediate areas.

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The input data is in a digital format describing the geometry of the pattern to be written on the surface. The 25 input data is often given in a very small address unit, e.g. 1 nanometer, while setting pixels in the SLM to either on or off gives a much coarser pattern. If a pixel on the SLM is projected to a $0.1 \mu\text{m}$ pixel in the image, a line can only have a width that is an integer number of 30 pixels ($n * 0.1 \mu\text{m}$ where n is an integer). An address grid of $0.1 \mu\text{m}$ was enough until recently, but the advent of so called optical proximity correction OPC makes a 35 grid of 1 - 5 nanometers desirable. In OPC the size of features in the mask are modified slightly to compensate for predicted optical image errors when the mask is used. As an example, when a mask with four parallel lines $0.8 \mu\text{m}$ wide is printed in a modern 4X reduction stepper (a

projection printer for semiconductor wafers) they will in a typical case print as lines 0.187, 0.200, 0.200, and 0.187 μm wide although they were intended to have the same width. This can be predicted by simulation of the 5 image formation and the user of the mask may use OPC to compensate in the mask. therefore he wants the first and last line in the mask to be $4 * 0.213 = 0.852 \mu\text{m}$ instead of 0.800 μm . With an address grid of 0.1 μm he cannot make the correction, but with 5 nm address grid or finer 10 such correction are possible.

In figure 5 the method for providing data for the SLM is shown in a flow diagram. The first step, S1, is to divide the pattern data for the pattern to be written into separate pattern fields. The pattern data is 15 preferably received in digital form. Thereafter, in step S2, the fields are rasterised, and thereby assigned different exposure values. These values are then corrected for nonlinear response, step S3, and pixel-to-pixel variations, step S4. Finally, the pixel values are 20 converted to drive signals and forwarded to the SLM.

The invention preferably uses intermediate values between the off-state and on-state to create a fine address grid, e.g. 1/15, 1/25, 1/50, of the size of a pixel. A printed feature consists of pixels in the on state, but along the edge it has pixels set to intermediate values. This is done by driving the pixels with other voltages than the on and off voltages. Since there are several cascaded non-linear effects (the position of the edge versus exposure at the pixels at the 25 boundary, the exposure vs. the deformation, and the deformation vs. the electric field) a non-linear transformation from the input data to the electric field is needed. Furthermore this transformation is calibrated 30 empirically at regular time intervals.

Figure 3 shows an array of pixels moving up and down like pistons, thereby creating a phase difference. The figure shows how the pixels are controlled to create the 35

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reflectivity in the inset. The bright areas have pixels with 0 phase, while dark areas are created by pixels with alternating +90 and -90 degree phase. The oblique boundaries between bright and dark areas are created by 5 intermediate values of phase. This is how an edge can be fine-positioned with a phase-type SLM. However, other types of SLM with intermediate values could be used in the same manner. The imaging properties with the phase SLM driven into intermediate values are complex and it is 10 far from obvious that the edge will be moved in figure 3. However, it has been shown by extensive theoretical calculations and experiments by the inventor, that the described effect is real.

To create a finer address grid the electronic 15 processing system is adapted to create one type of pixel map inside pattern features, another type of pixel map outside features, and intermediate pixel maps at a boundary, as shown in Figure 3, where the intermediate pixel map at a boundary is generated in dependence of the 20 placement of the boundary in a grid finer than that of the pixels of the SLM projected on the workpiece. The SLM and the projection system creates one exposure level inside features, another exposure level between features, and an intermediate exposure level at the boundary. The 25 intermediate exposure level is created using the capability of the SLM to modulate to multiple states. The response from driving signals to actual placement of the boundary is characterized and corrected for. It is empirically measured and a calibrating function is 30 computed and stored in the data processing and delivery system.

To further improve the address resolution the stage and the SLM are adapted to stitching exposure fields together along a direction not parallel to the coordinate 35 system of the SLM, typically 45 degrees. In particular the continuous movement of the stage or optical system takes place in a direction not parallel to the SLM, but

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typically at 45 degrees from the coordinate system of the SLM. It is also possible to have an SLM with non-orthogonal axes, in which case it is advantageous to have no axis parallel to the direction of motion.

5 Furthermore, to suppress line errors resulting from imperfections in the column and row drivers of the SLM of line error in the matrix itself it is effective to have the row and column lines at an angle to the direction of stitching, i.e. the vector between the centers of
10 stitched fields.

Additional refinement of the address grid is created by the overlaying of at least two exposures with modified data such that the combined exposure has intermediate values not possible to obtain in a single exposure.

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The design of the phase-type SLM

A cloverleaf mirror design, shown in fig 2c, as used in prior art is possible to drive to intermediate states between on and off states. However, when the integrated
20 complex amplitude is plotted as a function of deflection, it is seen that it never goes to zero completely but circles around zero, therefore having a non-zero minimum reflectivity with a varying phase angle. This is shown schematically by the line 701 in fig 7, where 703 indicates a position for a certain deformation value, and
25 ϕ being the associated phase angle. A thorough analysis of an image with some pixels set to intermediate states shows that the position of the edges in the final image are not stable through focus if the integrated phase
30 angle of the edge pixels is not zero. This is the diffraction effect analogous to the specular one shown in fig 4. In a preferred embodiment of the invention a new type of pixels with pivoting elements is used. Examples of such elements are shown in fig 2e-h. When the elements
35 pivots one end moves toward the light source and the other end away from it thereby keeping the average phase close to zero. This is shown schematically by the dashed

line 702 in fig 7. Furthermore the cloverleaf design has a problem of built-in stress created during the fabrication. This stress tends to give a partial deformation without an applied electric field. The built-in deformation is not perfectly the same in every pixel since it depends on imperfections during the manufacturing. In the cloverleaf design this difference from pixel to pixel creates a first-order variation of reflectivity. With pixel cells built from pivoting elements the same effect occurs, but gives a second-order effect. Therefore the uniformity is better in the projected image.

The design of the modulating elements and the exposure method are adapted to creating, for differently placed and/or differently oriented edges in the pattern, a symmetry in the aperture stop of the projection system. Inherent assymmetries between edges placed at different positions relative to the pixel grid can be reduced by overlaying at least two images with different placement 20 of the pixel grid relative to the pattern.

For a deflection type of SLM the symmetry relates to the intensity distribution in the aperture stop. Best is to have modulating elements that deflect the light symmetrically relative to the center of the aperture stop, or else can overlayed exposures with complementary deflection be used to create symmetry. With modulating elements with steerable deflection it is possible to create a constant geometrical realtion between the deflection at a pixel at an edge and the edge, i.e. 25 directing it in a direction perpendicular to the edge and toward the interior of the feature.

With a diffraction type SLM it is possible to create symmetry by overlaying exposures with opposite phase maps. Symmetry can be maintained if the complex amplitude 35 is everywhere real on the SLM, and pixels can be designed with the integrated complex amplitude being essentiaill real with values in the range -1 to 1. Many times it is

sufficient with amplitudes in the range -0.5 to 1. This is the case with the square pivoting micromirror elements in Figure 2e,f,g,h.

With access to a small negative amplitude to print in the background areas it is possible to enhance the resolution. In a more complex scheme it is possible to drive groups of adjacent pixels to combine in the image, and after being filtered by the imaging system, to give a desired real amplitude.

In order to preserve symmetry it is beneficial to have at least 2-fold symmetry and preferably 4-fold. Symmetry can be created for pixels not having an inherent rotational symmetry by multiple overlaid exposures. Furthermore, with a pixel design or exposure sequence giving a controlled real amplitude can be used for resolution enhancements. Dark lines can be given extra contrast if placed between areas with opposite phase and the edge of a feature can be improved by driving adjacent pixels inside the feature to higher positive amplitudes or adjacent pixels outside to negative ones.

Image enhancements.

There is a third advantage with a pivoting design: the cloverleaf does not reach full extinction, but a pivoting cell can more easily be given a geometry that gives full extinction, or even goes through zero and comes back to a small non-zero reflection, but with reversed phase. With better extinction there is greater freedom to print overlapping exposures, designing for a small negative value 702 gives better linearity close to extinction. Printing with a weak exposure, approximately 5%, in the dark areas, but with reversed phase can give an increased edge sharpness of 15 - 30 % and the ability to print smaller features with a given lens. This is an analog to so called attenuating phase-shifting masks that are used in the semiconductor industry. A related method of increasing the edge acuity is to set the pixels that

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are inside a feature a lower value and those near the edge a higher value. This gives a new type of image enhancement not possible with current projection of patterns from masks or by the use of projectors following
5 Nelson and Kück. The combination of a non-zero negative amplitude in the background and an increased exposure along the edges need not conflict with the creation of a fine address grid by driving edge pixels to intermediate values, since the effects are additive or at least
10 computable. When the pixels are substantially smaller than the feature to be printed there exists a combination of pixel values that creates all effects simultaneously. To find them requires more computation than the generation of a fine address grid alone, but in some
15 applications of the invention the ability to print smaller features can have a high value that pays for the extra effort.

In the case of a continuous mirror on a viscoelastic layer there is an inherent balancing of the average phase
20 to zero. Simulations have shown that the driving to intermediate values for fine positioning of feature edges work also for the continuous mirror. The non-linearities are smaller than with micromirrors. But for the method to work well the minimum feature has to be larger than with
25 micromirrors, i.e. have a larger number of addressed pixels per resolved feature element is needed. Consequences are a larger SLM device and that for given pattern the amount of data is larger. Therefore the
30 micromirrors have been chosen in a first and second embodiment.

In the invention a pixel with rotation-symmetrical deformation (at least two-fold symmetry, in a preferred embodiment four-fold symmetry) is used for two reasons: to give a symmetrical illumination of the pupil of the
35 projection lens and to make the image insensitive to rotations. The latter is important for printing a random logic pattern on a semiconductor wafer. If there is an x-

y asymmetry the transistors laid-out along the x axis will have a different delay from those along the y axis and the circuit may malfunction or can only be used at a lower clock-speed. The two requirements of image 5 invariance through focus and symmetry between x and y makes it very important to create and maintain symmetries in the optical system. Symmetry can be either inherent or it can be created by deliberate balancing of assymetric properties, such as using multiple exposures with 10 complementary assymmetric properties. However, since multiple exposures lead to reduced through-put inherent symmetrical layouts are strongly favoured.

15 Preferred embodiments

A first preferred embodiment is a deep-UV pattern generator for photomasks using an SLM of 2048 x 512 micromirrors. The light source is an KrF excimer laser with a pulsed output at 248 nanometers, pulse lengths of 20 approximately 10 ns and a repetition rate of 500 Hz. The SLM has an aluminum surface that reflects more than 90% of the light. The SLM is illuminated by the laser through a beam-scrambling illuminator and the reflected light is directed to the projection lens and further to the 25 photosensitive surface. The incident beam from the illuminator and the exiting beam to the lens are separated by a semitransparent beamsplitter mirror. Preferably the mirror is polarisation-selective and the illuminator uses polarised light, the polarisation direction of which is switched by a quarter-wave plate in front of the SLM. For x and y symmetry at high NA the image must be symmetrically polarised and a second quarter-wave plate between the beamsplitter and the projection lens creates a circularly polarised image. A 30 simpler arrangement when the laser pulse energy allows it is to use a non-polarising beamsplitter. The quarter-wave plate after the second pass through the beamsplitter is 35

still advantageous, since it makes the design of the beam-splitting coating less sensitive. The simplest arrangement of all is to use an oblique incidence at the SLM so that the beams from the illuminator and to the 5 projection lens are geometrically separated, as in figure 1.

The micromirror pixels are $20 \times 20 \mu\text{m}$ and the projection lens has a reduction of 200X, making one pixel on the SLM correspond to $0.1 \mu\text{m}$ in the image. The lens is 10 a monochromatic DUV lens with an NA of 0.8, giving a point spread function of $0.17 \mu\text{m}$ FWHM. The minimum lines that can be written with good quality are $0.25 \mu\text{m}$.

The workpiece, e.g. a photomask, is moved with an interferometer-controlled stage under the lens and the 15 interferometer logic signals to the laser to produce a flash. Since the flash is only 10 ns the movement of the stage is frozen during the exposure and an image of the SLM is printed, $204.8 \times 51.2 \mu\text{m}$ large. 2 milliseconds later the stage has moved $51.2 \mu\text{m}$, a new flash is shot 20 and a new image of the SLM is printed edge to edge with the first one. Between the exposures the data input system has loaded a new image into the SLM, so that a larger pattern is composed of the stitched flashes. When a full column has been written the stage advances in the 25 perpendicular direction and a new row is started. Any size of pattern can be written in this way, although the first preferred embodiment typically writes patterns that are $125 \times 125 \mu\text{m}$. To write this size of pattern takes 50 minutes plus the time for movement between consecutive 30 columns.

Each pixel can be controlled to 25 levels (plus zero) thereby interpolating the pixel of $0.1 \mu\text{m}$ into 25 increments of 4 nanometers each. The data conversion takes the geometrical specification of the pattern and 35 translates it to a map with pixels set to on, off or intermediate reflection. The datapath must supply the SLM with $2048 \times 512 \times 500$ words of data per second, in

practice 524 Mbytes of pixel data per second. In a preferred embodiment the writable area is maximally 230 x 230 mm, giving up to $230 / 0.0512 = 4500$ flashes maximum in a column and the column is written in $4500 / 500 = 9$ 5 seconds. The amount of pixel data needed in one column is $9 \times 524 = 4800$ Mb. To reduce the amount of transferred and buffered data a compressed format is used, similar to the one in Sandström et al. 90, but with the difference that a pixel map is compressed instead of segments with a 10 length and a value. A viable alternative is to create a pixel map immediately and use commercially available hardware processors for compression and decompression to reduce the amount of data to be transferred and buffered.

Even with compression the amount of data in a full 15 mask makes it highly impractical to store pre-fractured data on disk, but the pixel data has to be produced when it is used. An array of processors rasterise the image in parallel into the compressed format and transfer the compressed data to an expander circuit feeding the SLM 20 with pixel data. In the preferred embodiment the processors rasterise different parts of the image and buffer the result before transmitting them to the input buffer of the expander circuit.

25 A second preferred embodiment

In a second preferred embodiment the laser is an ArF excimer laser with 193 nm wavelength and 500 Hz pulse frequency. The SLM has 3072 x 1024 pixels of $20 \times 20 \mu\text{m}$ 30 and the lens has a reduction of 333X giving a projected pixel of $0.06 \mu\text{m}$. There are 60 intermediate values and the address grid is 1 nanometer. The point spread function is $0.13 \mu\text{m}$ and the minimum line $0.2 \mu\text{m}$. The data flow is 1572 Mbytes/s and the data in one column 230 mm long is 11.8 Gb.

35 A third preferred embodiment is identical with the second one except that the matrix of pixels is rotated 45 degrees and the pixel grid is $84 \mu\text{m}$, giving a projected

pixel spacing along x and y of 0.06 μm . The laser is an ArF excimer laser and the lens the reduction of 240. Because of the rotated matrix the density of pixels in the matrix is less and the data volume is half of the 5 previous embodiment but with the same address resolution.

Laser flash to flash variations

The excimer laser has two unwanted properties, flash-to-flash energy variations of 5% and flash-to-flash 10 time gitter of 100 ns. In the preferred embodiments both are compensated in the same way. A first exposure is made of the entire pattern with 90% power. The actual flash energy and time position for each flash is recorded. A second exposure is made with nominally 10 % exposure and 15 with the analog modulation used to make the second exposure 5 - 15% depending on the actual value of the first one. Likewise a deliberate time offset in the second exposure can compensate for the time gitter of the first one. The second exposure can fully compensate the 20 errors in the first, but will itself give new errors of the same type. Since it is only on average 10% of the total exposure both errors are effectively reduced by a factor of ten. In practice the laser has a time uncertainty that is much larger than 100 ns, since the 25 light pulse comes after a delay from the trigger pulse and this delay varies by a couple of microseconds from one time to another. Within a short time span the delay is more stable. Therefore the delay is measured continuously and the last delay values, suitably 30 filtered, are used to predict the next pulse delay and to position the trigger pulse.

It is possible to make corrections for stage 35 imperfections in the same way, namely if the stage errors are recorded and the stage is driven with a compensating movement in the second exposure. Any placement errors that can be measured can in principle be corrected in this way, partially or fully. It is necessary to have a

fast servo to drive the stage to the computed points during the second exposure. In prior art it is known to mount the SLM itself on a stage with small stroke and short response time and use it for fine positioning of 5 the image. Another equally useful scheme is to use a mirror with piezoelectric control in the optical system between the SLM and the image surface, the choice between the two is made from practical considerations. It is also possible to add a position offset to the data in an 10 exposure field, and thereby move the image laterally.

The second exposure is preferably done with an attenuating filter between the laser and the SLM so that the full dynamic range of the SLM can be used within the range 0 - 15 % of the nominal exposure. With 25 15 intermediate levels it is possible to adjust the exposure in steps of $15\% / 25 = 0.6\%$.

The response varies slightly from pixel to pixel due to manufacturing imperfections and, potentially, also from ageing. The result is an unwanted inhomogeneity in 20 the image. Where image requirements are very high it may be necessary to correct every pixel by multiplication with the pixels inverse responsivity which is stored in a lookup memory. Even better is the application of a polynomial with two, three or more terms for each pixel. 25 This can be done in hardware in the logic that drives the SLM.

In a more complex preferred embodiment several corrections are combined into the second corrective exposure: the flash to flash variation, flash time 30 gitter, and also the known differences in the response between the pixels. As long as the corrections are small, i.e. a few percent in each they will add approximately linearly, therefore the corrections can be simply added before they are applied to the SLM. The sum is multiplied 35 with the value desired exposure dose in that pixel.

Alternative illumination sources

The excimer laser has a limited pulse repetition frequency (prf) of 500 - 1000 Hz depending on the wavelength and type of the laser. This gives large fields with stitching edges in both x and y. In two other 5 preferred embodiments the SLM is illuminated with a pulsed laser with much higher prf, e.g. a Q-switched upconverted solid state laser, and with a continuous laser source scanned over the surface of the SLM, so that one part of the SLM is reloaded with new data while 10 another part is printed. In both cases the coherence properties of the lasers are different from the excimer laser and a more extensive beam-scrambling and coherence control is needed, e.g. multiple parallel light paths with different pathlengths. In some implementations of 15 the invention the light output from a flash lamp is sufficient and can be used as the light source. Advantages are low cost and good coherence properties.

In the preferred embodiment with scanning illumination two issues are resolved: the pulse to pulse 20 variation in time and energy, since the scanning is done under full control preferably using an electrooptic scanner such as acoustooptic or electrooptic, and many continuous laser have less power fluctuation than pulsed lasers. Furthermore the use of continuous lasers gives a 25 different selection of wavelengths and continuous lasers are less dangerous to the eye than pulsed lasers. Most important, however, is the possibility of reaching much higher data rates with a matrix with only a few lines since the scanning is non-critical and can be done with 30 100 kHz repetition rate or higher. Scanning the illumination beam is also a way of creating a very uniform illumination, which is otherwise difficult.

In some embodiments it is possible, and feasible, to use a flash lamp as the illumination source.

Light sources for EUV are based on radiation from a particle accelerator, a magnetic plasma pinch machine or the heating of a small drop of matter to extreme temperatures with a high-power laser pulse. In either 5 case the radiation is pulsed. The EUV radiation propagates only in vacuum and can only be focused by reflective optics. A typical pattern generator using an SLM has a small exposure field a modest requirement of optical power. The design of the optical system is 10 therefore relaxed compared to that of an EUV stepper, making it possible to use more mirrors and go to higher NA than in a stepper. It is anticipated that a high-NA lens will have a ring-shaped exposure field and it is 15 fully possible to adapt the shape of the SLM to such a field. With a wavelength of 13 nm and an NA of 0.25 it is possible to expose lines that are only 25 nm wide, and, using image enhancement as described below, even below 20 nm. No other known writing technology can match this 20 resolution and at the same time the writing speed that is made possible by the parallel character of an SLM.

Edge overlap

Since a two-dimensional field is printed for each flash and the fields are stitched together edge to edge 25 to edge the stitching is very critical. A displacement of only a few nanometers of one field will create pattern errors along that edge that are visible and potentially detrimental to the function of an electronic circuit produced from the mask. An effective way of reducing the 30 unwanted stitching effects is to print the same pattern in several passes but with a displacement of the stitching boundaries between the passes. If the pattern is printed four times the stitching error will occur in four positions, but with only a fourth of the magnitude. 35 In a preferred embodiment of the current invention the ability to create intermediate exposures is used together with an overlap band between the fields. The values are

computed during the rasterisation, although it could also be done during the expansion of the compressed data. Edge overlap reduces the stitching errors with much less throughput penalty than multipass printing.

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Modified illumination

In the first preferred embodiment the illumination of the SLM is done by an excimer laser and a light scrambler such as a fly-eye lens array to create an illumination that resembles that from a circular self-luminous surface in the pupil plane of the illuminator. In order to increase the resolution when printing with a specific projection system it is possible to use a modified illumination. In the most simple cases pupil filters are introduced in the pupil plane of the illuminator, e.g. with a quadrupole-shaped or annular transmission area. In a more complex case the same field is printed several times. Several parameters can be made to vary between the exposures, such as focus in the image plane, illumination pattern, data applied to the SLM and pupil filter in the pupil plane of the projection optics. In particular the synchronised variation of the illumination and a pupil filter can give an increased resolution, most notably if the pupil has a sector-shaped transmitting area and the illumination is aligned so that the non-diffracted light intercepts an absorbing patch near the apex of the sector

Linearisation of the response

30 For linearisation of the transfer function from data to edge placement here are essentially three ways to go:

- taking the non-linearity into account in the data conversion unit and generating an 8 bit (example) pixel values in the data conversion unit and use DACs

35 with the same resolution to drive the SLM. This is shown schematically in fig 8a, where R are relay signals and C are capacitors being provided on each

matrix element on the SLM. The SLM is indicated by the dashed line.

- to generate digital values with fewer values, e.g. 5 bits or up to 32 values, and translate them to an 8 bit value in a look-up table (LUT) and then feed the 8 bit values to the DACs.
- to use a 5 bit value and semiconductor switches to select a DC voltage that is generated by one or several high-resolution DACs. This is shown 10 schematically in fig 8b.

In either case it is possible to measure an empirical calibration function such that the response on the plate is linearised, when said function being applied at respectively the data conversion unit, the LUT or in 15 the DC voltages.

Which linearization scheme to use depends on the data rate, the precision requirements and also on the available circuit technology that may change over time. At the present time the data conversion unit is a 20 bottleneck and therefore it is not a preferred solution to linearise in the data conversion unit, neither to generate 8-bit pixel values. High-speed DACs are expensive and power-hungry and the most appropriate solution is to generate DC voltages and use switches. It 25 is then possible to use even higher resolution than 8 bits.

Description of a preferred pattern generator

Referring to figure 6, a pattern generator comprises 30 an SLM 601 with individual and multi-value pixel addressing, an illumination source 602, an illumination beam scrambling device 603, an imaging optical system 604, a fine positioning substrate stage 605 with an interferometer position control system 606 and a hardware 35 and software data handling system 607 for the SLM. For proper functionality and ease of operation it also contains a surrounding climate chamber with temperature

control, a substrate loading system, software for timing of stage movement and exposure laser triggering to achieve optimum pattern placement accuracy and a software user interface.

5 The illumination in the pattern generator is done with a KrF excimer laser giving a 10-20 nanoseconds long light flash in the UV region at 248 nanometer wavelength with a bandwidth corresponding to the natural linewidth of an excimer laser. In order to avoid pattern distortion
10 on the substrate, the light from the excimer laser is uniformly distributed over the SLM surface and the light has a short enough coherence length not to produce laser speckle on the substrate. A beam scrambler is used to achieve these two aims. It divides the beam from the
15 excimer laser in several beam paths with different path length and then adds them together in order to reduce the spatial coherence length. The beam scrambler also has a beam homogenizer consisting of a lens system containing a set of fly-eye lenses that distributes the light from
20 each point in the laser beam from the excimer laser uniformly over the SLM surface giving a "top-hat" light distribution. This beam scrambling, homogenizing and reduction of coherence is advantageous in all SLM printers. Depending on the actual circumstances
25 implementations using beam-splitters and combiners, diffractive elements, optical fibres, kaleidoscopes, lenslet arrays, prisms or prism arrays or integrating spheres can be used, as well as other similar devices in combinations which split and combines the beams to create
30 a multitude of mutually incoherent light fields impinging on the SLM.

 The light from the SLM is relayed and imaged down to the substrate on the substrate stage. This is done using a Schlieren optical system described by Kück. A lens l_1 with the focal width f_1 is placed at the distance f_1 from the SLM. Another lens l_2 with the focal length f_2 is placed at the distance $2 \times f_1 + f_2$ from the SLM. The

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substrate is then at a distance $2 \times f_1 + 2 \times f_2$ from the SLM. At the distance $2 \times f_1$ from the SLM there is an aperture 608 which size determines the numerical aperture (NA) of the system and thereby the minimum pattern

5 feature size that can be written on the substrate. In order to correct for imperfections in the optical system and the substrate flatness there is also a focal system that dynamically positions the lens l_2 in the z direction with a position span of 50 micrometers to achieve optimal

10 focal properties. The lens system is also wavelength corrected for the illuminating wavelength of 248 nanometers and has a bandwidth tolerance of the illuminating light of at least ± 1 nanometer. The illuminating light is reflected into the imaging optical

15 system using a beamsplitter 609 that is positioned immediately above the lens l_1 . For a demagnification factor of 250 and an NA of 0.62 it is possible to expose pattern features with a size down to 0.2 micrometers with a good pattern quality. With 32 levels from each SLM-

20 pixel the minimum gridsize is 2 nanometers.

The pattern generator has a fine positioning substrate stage with an interferometer position control system. It consists of a moveable air bearing xy table 605 made of zerodur for minimum thermal expansion. A

25 servo system with an interferometer position feedback measuring system 606 controls the stage positioning in each direction. In one direction, y, the servo system keeps the stage in fixed position and in the other direction, x, the stage moves with continuous speed. The

30 interferometer position measuring system is used in the x-direction to trigger the exposure laser flashes to give uniform position between each image of the SLM on the substrate. When a full row of SLM images are exposed on the substrate the stage moves back to the original

35 position in the x direction and moves one SLM image increment in the y direction to expose another row of SLM

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images on the substrate. This procedure is repeated until the entire substrate is exposed.

The SLM images overlaps with a number of pixels in both the x and y direction and the exposure data pattern 5 is locally modified in the overlap pixels to compensate for the increased number of exposures that result in such overlap areas.

Variations in pulse to pulse intensity from the excimer laser is compensated by using two-pass exposure 10 of the pattern where the first pass is done using a nominal 90% intensity of the correct intensity. In the first pass, the actual intensity in each laser flash is measured and stored. In the second pass, the correct intensity for each SLM image exposure is then used based 15 on the measured intensity values from the first pass. In this way it is possible to reduce the influence from pulse to pulse intensity variations from the excimer laser by one order of magnitude.

20 Correction

The functionality of the SLM is described extensively elsewhere in this text. It has 2048 x 256 pixels with pixel size of 16 micrometers and it is possible to address all pixels within 1 millisecond. The 25 SLM is rigidly mounted in a fine stage. This fine stage is moveable 100 microns in the x and y directions with accuracy better than 100 nanometers between each flash exposure. The fine positioning of the SLM is used to correct for position inaccuracy of the substrate 30 positioning stage to further reduce pattern-stitching errors. In addition to the x-y positioning, there is also a rotational possibility of the SLM stage in order to expose a pattern on a substrate with an angle other than the one specified by the substrate stage coordinate 35 system. The purpose for such rotation is to create the possibility of incorporating substrate alignment feasibility for substrates with an already existing

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pattern where additional features shall be added. It is possible to measure the exact position of the substrate on the stage after loading it using an off axis optical channel and/or a CCD camera looking through the lens to

5 determine the system coordinates for a number of alignment marks existing on the substrate. During exposure, the stage position is then corrected in the x- and y-directions based on the measured positions of the alignment marks. Rotational alignment is achieved by

10 using the stage servo system to follow the rotated coordinate system and also rotating the SLM fine stage as described. The possibility of rotating the SLM makes it also possible to write in a distorted coordinate system, such as to compensate for subsequent warpage of the

15 pattern.

Further, the means for rotating the coordinate system of the pattern to be written could comprise means for imposing a rotation to the digital description supplied to the electronic data processing and delivery system. Hereby, the data is converted to a rotated digital description before it is forwarded to the electronic data processing and delivery system. Alternatively, it is possible to impose the rotation to the modulator signals supplied by the electronic data processing and delivery system. In this case, the modulator signals are converted after rasterization, but before they reach the modulator. The conversion is preferably made in real-time.

The same method for rotating the coordinate system could be used for other types of pattern writer systems as well, such as raster scanning laser beams. Especially, it could be used for systems using acousto-optic deflectors, such as the system described in EP 0 467 076 (Sandström et al.), said document hereby incorporated by reference. However, in such a scanning writer system, the rotation is preferably imposed by rotating the deflector. An example of a mechanism for rotating the image of the

modulator and adjusting the azimuth angle to compensate for the rotational angle between a first layer relative to the second is illustrated in fig 10. The deflector is in this example mounted on an azimuth mechanism 1006. The 5 azimuth mechanism comprises an actuator 1007, such as a stepping motor and a connector 1008, such as a lever arm connected to the deflector for controlling the orientation of the deflector, and thereby the azimuth angle. A similar mechanism may be used for orientation of 10 a modulator. The stage is then operated as discussed in the previous.

However, other means for rotating the coordinate system of a pattern to be written are also feasible. For example the means for rotating the coordinate system of 15 the pattern to be written could comprise an optical element for rotating the image projected from the modulator to the workpiece. To this end a Dove prism could be used. However, it is also possible to use an analog arrangement of reflecting surfaces, as shown in 20 fig 15, or the like. Hereby, a controlled rotation could be imposed to the image projection from the modulator before it reaches the workpiece.

The above-mentioned rotation is particularly useful when a second pattern is to be written on a workpiece 25 already comprising a first written pattern. In this case, the workpiece may need to be replaced in the same writing apparatus, or the second pattern may even be written with a writing equipment other than the one used for writing the first pattern. In this case it is of uttermost 30 importance to diminish rotational deviations between the patterns.

The above correction means and measures could be used in the production of masks and reticles, but could also be applied in direct writing systems.

Alignment

In order to control the rotation of the second pattern in an appropriate way, the rotational deviation between the first, already existing pattern and the 5 second pattern to be written is preferably detected by means of a detection system. However, it could also be of use in other applications to control the rotational deviation adequately. Such a detection system preferably comprises means for detecting the position of at least 10 one alignment mark on the workpiece, and further relates this measured position to a coordinate system of the writing apparatus.

With reference to Fig 9, the alignment mark preferably comprises at least two lines 901 in different, 15 predetermined and non-parallel directions. In a preferred embodiment the alignment mark comprises a snake mark 902, i.e. a several lines connected in a zigzag like fashion. For example, the snake mark could comprise six 20 interconnected lines, with an at least slightly acute angle between adjacent lines. The advantage of such snake marks is that they can be used to determine both rotation and position of the mark.

The alignment mark preferably also comprises a search mark 903, which enables a faster and more 25 efficient location of the alignment mark with an overview search. The search mark could comprise longer and thicker lines 904 than the snake mark. Preferably, the search mark comprises two non-parallel lines 904 arranged relatively close to each other.

30 The total length of the snake mark and the search mark could be about 500-600 μm .

Several alignment marks could be arranged on 35 different positions on the workpiece. For example, four alignment marks could be arranged distributed on the periphery of the workpiece, such as in the corners or preferably on the sides between the corners.

The mark detection system could comprise an off axis optical channel for locating and measuring the position of the alignment marks on the workpiece, and further relate this measured position and rotation to a 5 coordinate system of the writing apparatus. However, in a preferred inventive embodiment, the detection and alignment system at least partly uses the same beam path as the writing beams, and preferably the same lens as is used for the writing operation is used for the detection 10 as well.

With reference to Fig 10, the detection and alignment system comprises a light source 1001, and preferably a laser emitting light of a wavelength which could transmit the resist layers and the like arranged 15 above the alignment mark on the workpiece. Further, the emitted light preferably has a wavelength not affecting the photosensitive layer of the workpiece. In a preferred embodiment, a wavelength of 532 nm is used.

The reflected light is then studied for detection 20 and alignment. Preferably, the dark field signal of the reflected light is studied, because this signal enhances the visibility of details. The specularly reflected light is then filtered out and only the scattered light is collected and focused on a detector, such as a PIN 25 detector. However, other alternative solutions are feasible to achieve contrast enhancement, such as any one of the types used in light microscopy. For example, one of the following contrast enhancement methods may be used:

- 30 • Bright field, where the reflected light is detected;
- Dark field, whereby light intensity decreases but an improved edge discrimination is achieved;
- Confocal imaging, whereby a better lateral resolution and depth resolution is achieved;
- 35 • phase contrast imaging, whereby a better depth resolution is achieved;
- Nomarski; and

- Lateral interference.

The contrast enhancement improves the signal-to-noise ratio. It is especially useful where an improved precision and exactness is required, in direct writing 5 applications and when chemical mechanical polishing (CMP) is used.

A mechanical shutter 1002 is further arranged in front of the laser 1001 to switch off the beam when not used. The shutter could be vacuum activated, and is 10 controlled by means of a vacuum control unit 1003.

The laser beam is preferably focused on a narrow spot of about 1 μm in diameter on the substrate using the same focus lens 1004 as the writing beam. This could be arranged by adding a beam splitter cube 1005 in the beam 15 path for the writing beam ahead of the final lens 1004.

In order to calculate the displacement and the rotation of the first pattern, an accurate positioning of the alignment marks has to be determined. To locate the alignment marks the substrate is driven with the 20 mechanical positioning system, as described above, to scan the alignment beam over the substrate in consecutive strokes. The values from the stage position detectors, such as x- and y-interferometers, and from alignment detectors 1009, such as one or more PIN-detectors, are 25 hereby collected in steps during the scan. The point-by-point measurements will build up a matrix from which the alignment marks can be located. However, in a preferred embodiment only changes are stored, i.e. positive and negative edges. Other types of detectors are however 30 feasible as well, such as charged coupled device (CCD) detectors. Preferably, an overview first scan is made with a CCD or the like, for locating the alignment marks, where after a PIN-detector is used for more detailed 35 measurement. It is especially preferred to use a detector with a split detection area, such as a detection area divided into four detection fields. Hereby, edges becomes more easily detectable.

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Preferably, the marks are precisely detected in a fashion that does not affect or expose the resist. For example, light of a wavelength of 248 nm does normally expose the resist, whereas light of a green light wavelength (e.g. 532 nm) is non actinic, i.e. does not expose the resist. However, it may prove difficult to optimize the final lens for 532 nm, resulting in a poor performance. A way to solve this problem is to use only a slight part of the available exposure field, preferably less than 20%. Within such a small field, the wavefront errors at e.g. 532 nm could be corrected by means of special optics. Further, a reduced field also alleviates the problem with field aberration distortion, such as distortion, astigmatism and focus surface curvature.

Such a field reduction could be achieved with the systems as illustrated in fig 13 and 14. Both systems could be incorporated in the system described above, and especially the system described with reference to fig 10. In the system as illustrated schematically in fig 13, the final lens assembly 1004 is optimized for the writing light, e.g. with a wavelength of 248 nm. Further, the laser 1001 emits light, e.g. of the wavelength 532 nm. The emitted light is focused on a modulator 1301. This modulator may be an acousto optic modulator, but could also be other types of modulators, such as the mechanical shutter 1002 illustrated in fig 10. Thereafter, the light is projected on the substrate through the final lens assembly 1001, and is reflected back on the detector 1009. The detector could preferably be synchronized with the modulator. Between the detector 1009 and the final lens assembly 1004 correcting optics 1302 is preferably arranged.

In the alternative embodiment illustrated schematically in fig 14, the setup is essentially the same as in the system described above. However, in this case, a small angle scanner 1401 is used instead of the modulator. This small angle scanner scans the beam within

the small area of the reduced field. The scanner may e.g. be a acousto optic x-y deflector, such as NEOS, Florida, or a small galvanometer mirror which is tilttable in two directions (x and y directions).

5 When the marks have been located, they have to be accurately positioned. A more thorough scanning is then performed over the located mark. The values from the x and y interferometer and from the PIN detector is then collected in greater detail. The result could then be
10 used to determine an accurate rotation and position of the mark.

A method of alignment according to the invention is schematically illustrated in fig 11. The method starts at 1101, and at first it is determined whether the alignment 15 parameters are adequately defined, 1102. If not, parameters are read from a file, 1103. The parameters indicate what is to be searched and how the search should be performed. The items to be searched could be defined by parameters identifying the alignment marks. The 20 alignment mark may be of the form discussed in the foregoing. Preferably, the alignment mark are grouped in accordance with geometry, such as circles, lines or more complex combined forms. Each such group is preferably predefined in code format in the parameter file, and with 25 a set of parameters indicating the dimensions of the mark and/or group of marks. How the search should be performed may be a specification of one or several of: the tolerances for the placement of the mask in the system, for translation as well as rotation, the type of mask 30 being used, a maximum number of scan lines for the mark, the form of the signal, polarity and dynamic effects at the edges. Preferably, the search parameters identifies whether to search for negative or positive edges in the signal, how long the edges should be and a minimum 35 amplitude to be detected. This makes it possible to balance away differences for one and the same edge, and

makes the measuring independent on the exact edge position on the signal edge.

Most parameters may be set automatically by means of a computer program, but the parameters may also be 5 manually adjusted. The parameter file may also comprise statistics for a measured signal.

Subsequently, it is determined whether the statistics for the measured signals are properly defined, 1104. The statistics could comprise information about the 10 noise, the background level, maximum and minimum levels, signal edge lengths, etc. If not enough statistic data is available, such information may be read from a file, or measured. When measuring, a scan is performed in a line over the mark, 1105. Thereafter, the statistics for said 15 line is calculated, 1006. Then it is determined whether the statistics data is enough in step 1107. If not, steps 1105 to 1107 is repeated.

The search for the marks are thereafter performed by scanning in lines over the substrate, 1109. After each 20 scan, the signal is processed to identify edges in the scan line, 1110. After each scan, it is determined if enough data is collected, 1111, and steps 1109-1111 are repeated until enough data is collected. Further, the next scan line to be performed could hereby be determined 25 in dependence on the result from the previous scan lines. Hereby, the required number of scan lines could be kept low, rendering the search fast and effective. In the processing of the scan lines, edges are preferably only searched for in positions where edges are likely to be 30 found. Hereby, the search process becomes faster, and the problem with disturbing noise between the edges is alleviated.

When an adequate number of edges have been identified and calculated, the position of the alignment 35 mark is calculated, 1112. Depending on the form of the alignment mark, different search and identification methods may be used. E.g. for an alignment mark

comprising two intersecting lines, a linear interpolation of the edges may be performed, whereby the intersection point may be calculated. The output from the search process is the position of the mark, 1113. Then it is 5 determined whether the parameter and statistics files should be completed, 1114, and if so, the identified parameters and statistics is saved in a file, 1115. Then, the alignment method is completed, 1116.

The measured positions for the alignment marks could 10 be used to determine rotation, translation, differences in scale and/or differences in orthogonality, of a first, already written layer relative to a second layer. The differences in scale and orthogonality are especially important to determine when different layers are written 15 using different writing equipment. Differences in scale may also occur if the writing conditions for the writing of the different layers differs in other ways, such as different temperatures.

Further, it may be necessary to measure an offset 20 between the light beams used during the alignment and the writing beam. This difference in positioning must normally be compensated during the writing of different layers. Further, the offset is likely to vary over time, and should therefore preferably be measured regularly.

25 This offset could be determined in a similar manner as the alignment. To this end, the alignment mark discussed above could be used, or a separate beam measuring mark. Such a measuring mark may comprise four lines intersecting in a common intersection point, as 30 illustrated in fig 12. The beams are preferably evenly distributed with an angle of 45° between every pair of adjacent lines. The measuring mark need not comprise a search mark, since the position of the search mark is previously known. Accordingly, the measurement could be 35 performed in a limited, predetermined area of the raster, i.e. representing a fixed position on the stage.

For the offset measuring, a special measuring light beam may be used. Alternatively, the writing light may be used. For the measuring, a detector 1009', such as a PIN detector, could be used (see fig 10).

5 For the measuring, the stage, i.e. substrate table, could be positioned to allow a micro sweep to begin a distance from the mark corresponding to about the width of the lines in the mark. A stage movement in a first direction (X) is then started, and preferably

10 simultaneously the beam is scanned in a second direction (Y). Edges are identified in the reflected light, as in the alignment method discussed above. Every line in the mark that is passed gives rise to a pair of edges. The position in the X-direction could be provided by x-

15 positioning means for the stage, whereas the position in the Y-direction could be determined by the number of pulses between the start of the sweep and the edges, multiplied with the pixel size. The position of a line could then be determined by calculating a mean value

20 between the line edges.

After the sweep over the mark, a large number of positions for the lines have been collected. This position data could then be used for line interpolation calculations for determining the common intersection point. Hereby, the positioning of the light with the mark as a reference has been determined. The above discussed method and means for alignment and positioning could be used in the production of masks and reticles, but could also be applied in direct writing systems.

30 An arbitrary data pattern of an arbitrary format is transformed into a compressed rasterized pixel map with 32 (5 bit) gray levels per pixel in a pattern rasterizer 610. Since the grayscale steps of an exposed pixel is not linear in response to the voltage applied to the pixel electrode, the input data is linearized in a pixel linearizer 611 so that the 32 gray levels correspond to a

uniform increase in exposure dose for each successive level. This is done using 8-bit digital to analog converters (DAC) 612 where each gray level from the pixel map selects a voltage from the DAC's according to a 5 previously empirically calibrated linearization function. An additional offset in the choice of analog level from the DAC's is made using a lookup table where each value corresponds to an SLM pixel and each such value corrects for anomalies of the corresponding pixel. The calibration 10 values in the lookup table are generated using an empirical calibration procedure where a series of test patterns are sent to the SLM and the resulting exposed patterns are measured and used for individual pixel correction. This means that each gray level in the pixel 15 map selects an analog voltage generating a pixel deformation for every corresponding SLM pixel to give the correct exposure dose.

20 References

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